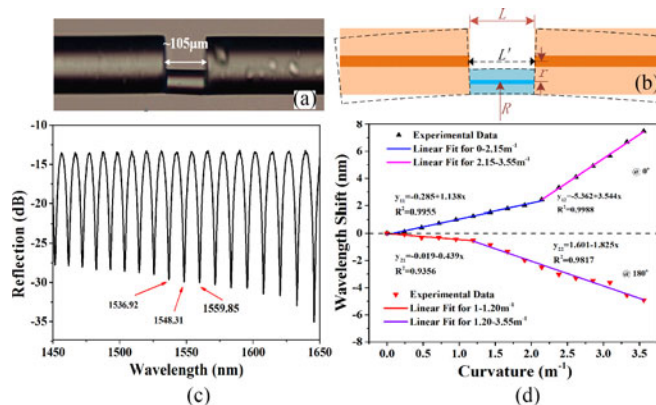


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Abstract: A bidirectional bend sensor based on U-shaped Fabry-Perot interferometer (UFPI) is experimentally demonstrated. The UFPI is constructed by eccentrically splicing a section of microfiber between two cleaved standard single mode fiber end faces serving as mirrors. A preliminary theoretic analysis of bending response of UFPI is presented. The bend and temperature sensing properties are measured. The theoretical and experimental investigation demonstrates the bending direction discrimination and the monotonous sensing characteristic in a single direction along or opposite to the cavity opening direction. The proposed bend sensor with more compact ($\sim 105 \mu\text{m}$ in length) and easier fabrication presents a high contrast of the interferometer fringes and low temperature sensitivity of $1.21 \times 10^{-3} \text{ nm}/^\circ\text{C}$.

Index Terms: Bend sensor, Fabry-Perot interferometry (FPI), optical fiber sensors.

1. Introduction

A fiber-based Fabry-Perot interferometer (FPI) with mirrors separated by air is usually defined as extrinsic FPI (EFPI) [1], which has been intensively investigated for various applications in the physical [2], [3], chemical [4], [5], and biological [6], [7] sensing fields, due to their unique characteristics such as simple configurations, compactness, and endurance for high temperature and high pressure environments [8], [9]. Many types of EFPI have been proposed, such as bonding two cleaved fibers into a small-diameter tube [10], splicing a hollow-core fiber or hollow-core photonic crystal fiber between two standard single-mode fibers (SMFs) [11], [12], inducing a rectangular air cavity during splicing SMFs [9], forming a spherical air micro-cavity by splicing a photonic crystal fiber with an SMF or splicing two SMFs [13]–[15], and ablating a cavity in the SMF by femtosecond

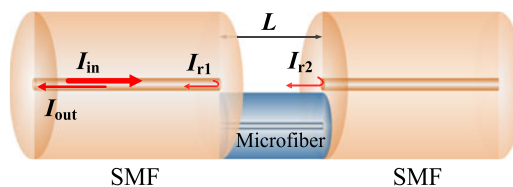


Fig. 1. Schematic of UFPI. The two end faces of the SMF serve as mirrors, and the microfiber is the connecting arm.

laser [16]. These EFPIs are usually employed as strain, refractive index, and high temperature sensors.

The measurement of curvature is likewise attracting intense interest in the fiber sensing field, because that the bending deformation is of great significance in the area of aerospace, machinery, and building structural health monitoring [17], [18]. Several fiber-based bend sensing methods have been proposed and achieved by mainly using fiber Bragg grating [19], [20], long-period grating [21], [22], and fiber-mode interferometer [23], [24]. However, the study on bending measurement employing EFPI is not sufficient, and it is difficult to look up the reports on this topic, which may result from the comprehensive action of a difficulty to bent the minisize EFPI, low bending sensitivity, poor mechanical strength, and so on.

In this paper, we present a bidirectional bending sensor employing the EFPI fabricated by splicing a section of microfiber with two SMF. The opening air cavity between two SMF end faces serves as the FP cavity and a direct sensing head. The microfiber is prepared by tapering SMF to around $54\ \mu\text{m}$ in diameter to avoid touching the SMF core during the eccentrically splicing. The proposed FP cavity possesses an asymmetric structure and displays a U-like shape, and thus named as U-shape FPI (UFPI) in this paper. An approximately theoretic analysis is obtained. The theoretic result suggests a capability of detecting the bending amplitude and determining the sense along or opposite to the cavity opening direction. The bending and temperature sensing characteristics of UPI are measured. When the UFPI is bent, the interference fringes dips display a blue or red shift according to the bend vector along or opposite to the opening direction of the cavity, and the wavelength shift monotonously changes with respect to curvature in a single direction. The temperature sensitivity is only $0.00121\text{nm}/^\circ\text{C}$, which indicates a higher precision of bending measurement than that of other bend sensors based on Fiber grating [19]–[22] and interferometry [23], [24].

2. The Design of UFPI and Its Sensing Principle

Fig. 1 depicts the schematic of the proposed UFPI which is composed of two cleaved SMF end faces as mirrors and a section of microfiber as a connector. The microfiber is spliced with the two end faces by the arc discharge fusion to enhance the mechanical strength of UFPI. In order to make sure that the light propagation comply with the principle of FPI, the microfiber is eccentrically spliced to the SMF end faces to avoid touching the SMF cores.

When propagating through the UFPI, the incident light I_{in} is respectively reflected by two mirrors and the reflected light interferes with each other in the SMF core resulting in an interference pattern at the output. Because of the low reflectivity of air and silica interface, the rigorous multiple beams interference of FPI is approximately simplified as double beams interaction, and thus the total output intensity I_{out} of the reflected light after passing through the UFPI can be written as

$$I_{\text{out}} = I_{r1} + I_{r2} + 2\sqrt{I_{r1}I_{r2}} \cos(4\pi n_{\text{air}}L/\lambda) \quad (1)$$

where I_{r1}, I_{r2} is the first reflected intensity at the two reflectors, respectively; L is the length of microfiber and the U-shape cavity; n_{air} is the refractive index of air; and λ is the free space wavelength of the input laser beam. When $4\pi n_{\text{air}}L/\lambda = (2m + 1)\pi$, $m = 1, 2, \dots$, the interference dips appear

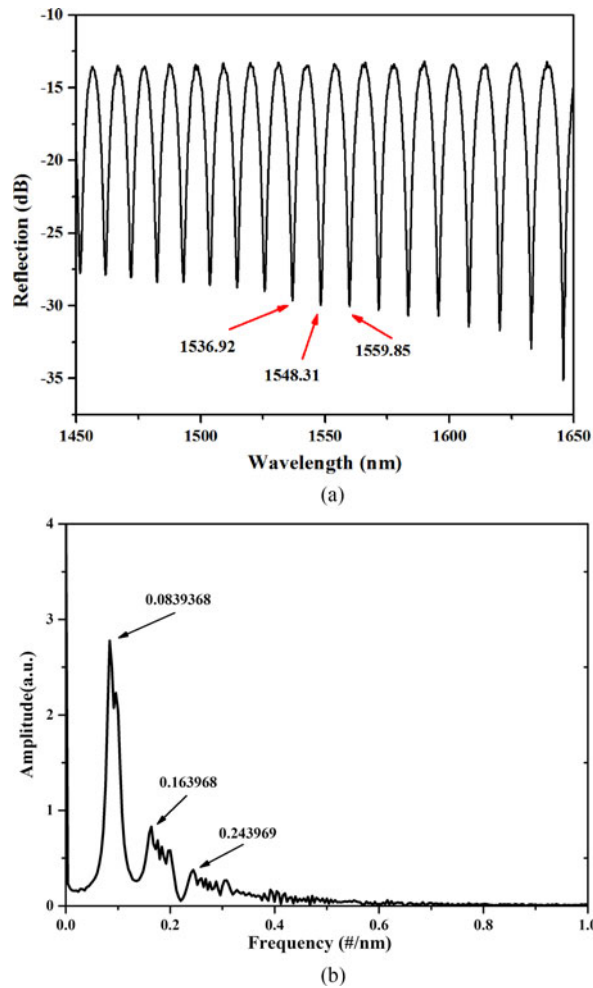


Fig. 2. (a) Interference spectrum of UFPI with an assistant microfiber of 105 μm in length and 54 μm in diameter and (b) its space frequency spectrum.

at the wavelengths λ_m satisfied by

$$\lambda_m = \frac{4\pi n_{\text{air}} L}{(2m + 1)\pi} \quad (2)$$

and the wavelength difference between adjacent dips [defined as free spectral range (FSR)] is expressed by

$$FSR = \frac{\lambda_m \lambda_{m-1}}{2\pi n_{\text{air}} L}. \quad (3)$$

In the interference pattern of UFPI depicted in Fig. 2(a), the position and separation of a series of dips are determined by (2) and (3), respectively. A fast Fourier transform is operated on this reflected spectrum to offer a deep sight into the frequency components as shown in Fig. 2(b). From the proportion of amplitude possessed by every frequency component, it can be described as the power of the reflected light is mainly concentrated in lowest frequency component, and the proportion of that in high-frequency ones quickly fade away with the increase of frequency. Obviously, the power in the lowest frequency component mainly results from the first reflection of UFPI, and the light power of high-frequency ones is induced from multiple reflection and can be

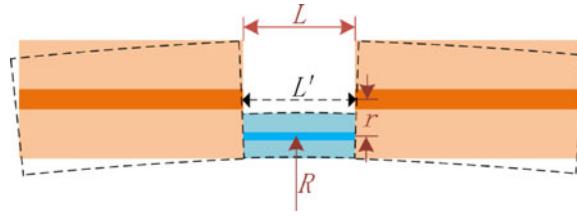


Fig. 3. Schematic diagram of UFPF under bending in 0° direction. L is the original cavity length, R is the bend radius of microfiber, r is the eccentricity distance between two cores of the microfiber and SMF, and L' is variational cavity length under bending.

neglected in an un-strict theoretic description as the preceding assumption on the double beam interference.

When the UFPF is subjected to external perturbations, the refractive index n_{air} inside the cavity or the cavity length L will variate, as a result, the dips position and the intensity of the interference spectrum correspondingly change. Therefore, the environment parameters can be monitored by tracking the variations of the reflected spectrum. When a bend is applied to the UFPF, the refractive index of air in the cavity keeps a constant, but the cavity length will be changed because of the geometric deformation. From the (2), the wavelength shift $\Delta\lambda_m$ of the reflected spectrum rooted in the variation of cavity length ΔL can be derived as

$$\Delta\lambda_m = \lambda_m \Delta L / L. \quad (4)$$

Since ΔL is directly related to the bending radius R via a geometric transformation, an intuitionistic relationship between $\Delta\lambda_m$ and R can be expected.

A bending UFPF is schematically shown in Fig. 3. For a convenient description, the bend opposite to the cavity opening direction as illustrated by a dash line in Fig. 3 is denoted 0° direction, and the reverse direction, i.e., along cavity opening direction, is named as 180° direction. Other geometry parameters marked in Fig. 3 are also described as follows: L is the original cavity length, R is the bend radius of microfiber, r is the eccentricity distance between two cores of the microfiber and SMF, and L' is the variational cavity length under bending.

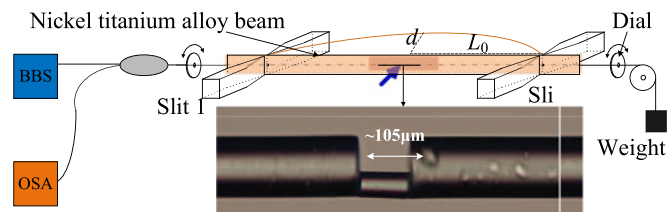
In this work, the microfiber length, i.e., the original cavity length L is assumed to be a constant. L' is approximately equal to the arc length between two end faces of SMF cores under small curvature. Thus, the actual bending radius of L' is $R + r$ in 0° direction and $R - r$ in 180° direction. In the state of bending free, $L' = L$. When the UFPF is bent, L' will be elongated or reduced according to the bending direction. Therefore, a relationship between L' and R can be built as $L'/(R \pm r) = L/R$ for a same sector angle. And then, $\Delta L = L' - L = \pm rCL$, where, $C = 1/R$ represents the bending curvature. Involving (4), $\Delta\lambda_m$ can be rewritten as

$$\Delta\lambda_m = \pm r\lambda_m C. \quad (5)$$

As can be seen from (5), a linear response of wavelength shift $\Delta\lambda_m$ to curvature C is presented, and it is noted that the red or blue shift of the wavelength is directly determined by the bending direction. When the UFPF is bent to 0° direction, the direct ratio relationship of $\Delta\lambda_m$ to C is valid, and thus the corresponding interference fringes shift towards longer wavelength. In contrast, the inverse ratio relationship is effective for 180° direction, and the corresponding interference fringes shift towards shorter wavelengths. Thus, the proposed UFPF-based bending sensor can tell the bending directions and evaluate the bending amplitude simultaneously.

3. Experiment Result and Discussion

The UFPF can be fabricated by the method presented in [4], which is summarily described as follows: First, a section of standard SMF (Corning SM-28e) is tapered to a microfiber with a desire waist diameter by the flame-brushing technique [25]. Second, the microfiber is cut off by a fiber cleaver



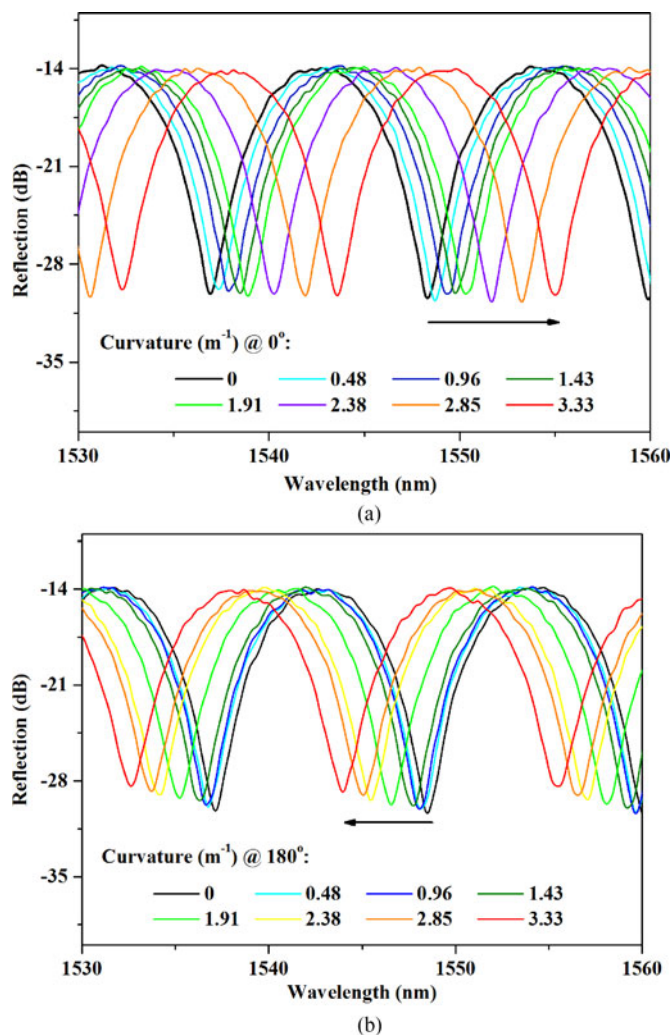


Fig. 5. Evolution of reflection spectra of the UFPI bent (a) to 0° and (b) to 180° direction.

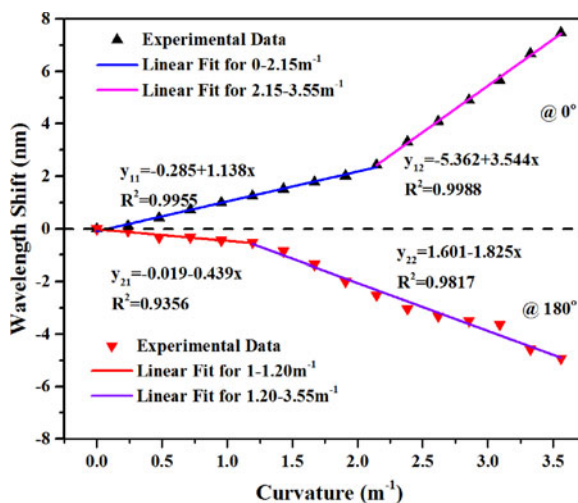


Fig. 6. Response of wavelength shift to curvature in 0° and 180° directions.

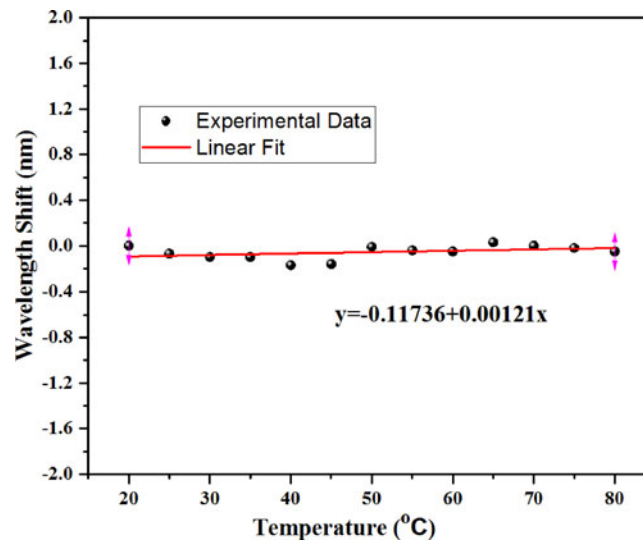


Fig. 7. Response of wavelength shift to temperature for a new UFPI sample with an assistant microfiber of 173 μm in length and 55 μm in diameter.

1.138 nm/m^{-1} and 3.544 nm/m^{-1} in the ranges of 0–2.15 m^{-1} and 2.15–3.55 m^{-1} , respectively. For the 180° direction, the bending sensitivities are $-0.439 \text{ nm}/\text{m}^{-1}$ and $-1.825 \text{ nm}/\text{m}^{-1}$ in the ranges of 0–1.20 m^{-1} and 1.20–3.55 m^{-1} , respectively. Although the ununiform sensitivity may induce some obstructions, the proposed bending sensor possesses a potential value in practical application for the characteristics of direction discrimination and monotonous response of wavelength shift to curvature.

The temperature behavior of this type of UFPI is also investigated. A new UFPI with the assisted microfiber dimension of 173 μm in length and 55 μm in diameter is heated in an electric furnace from 20 °C to 80 °C in air with an interval of 5 °C. The wavelength shift data were plotted with respect to temperature in Fig. 7, and subjected to linear fitting. The temperature sensitivity of the UFPI is around $1.21 \times 10^{-3} \text{ nm}/\text{°C}$, which is a fairly low response.

4. Conclusion

We have proposed and investigated a bidirectional bending sensor based on an in-fiber U-shaped Fabry-Perot cavity. Both results of the theoretical analysis and experimental study verify the bending direction dependence and monotonous sensing characteristic at a single direction. The theoretical analysis for the proposed UFPI presents that the sensitivity of the bending sensor is related to the distance between the two cores center of microfiber and SMF end faces, which indicates a new sight into improve the performance of bend sensors based on UFPI. Moreover, the cavity is constructed by just eccentrically splicing a section of microfiber into two SMF end faces and thus, is easy to fabricate and costless. The sensing unit is at the order of 100 μm in length, which indicates a competitive compact size. The low temperature sensitivity will deduce the effect of the crossing-sensitivity and thus improve the bending measurement precision in practical application.

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